



Incompressible Flows

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Fluids and gases

Fluid (flowing medium): gas or liquid

Solid body : Liquid : Gas (Steam) : dedicated volume, dedicated shape

- dedicated volume, no dedicated shape
- no dedicated volume, no dedicated shape



Container with liquid



Container with gas



here: No flow, No external forces besides gravity





Fluids and gases

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Experiment: Increasing load $F \rightarrow F + dF$, $p \rightarrow p+dp$ $V \rightarrow V + dV$ (with dV < 0) $\rho \rightarrow \rho + d\rho$ $\frac{d\rho}{\rho} = \gamma_T \frac{dp}{p} \Leftrightarrow \frac{p}{\rho} = \gamma_T \frac{dp}{d\rho}$ Isothermal Compressibility coefficient

Water
$$\gamma_T = 45, 4 \cdot 10^{-6}$$

Ideal gas $\gamma_T = 1$
weil für T = const $\rightarrow \frac{p}{\rho} = RT = const. = \frac{dp}{d\rho}$

The compressibility of liquids is several orders of magnitude smaller compared to gases











Fluids and gases

Compressibility of a gas flow







Example: Incompressible Fluid

Flow around a car







Example: Incompressible Fluid

Flow around a car







Example: Incompressible Fluid







Compressible Fluids







Compressible Fluids

Speed of sound

- Water: appr. 1400 m/s
- Air: appr. 330 m/s
- Speed of sound in water decreases significantly with dissolved air







Compressible Fluids

Example: Compressible pipe flow

Eigenfrequencies:

1st Eigenfrequency: $f_1 = a/(4L)$ 2nd Eigenfrequency: $f_2 = 3a/(4L)$ 3rd Eigenfrequency: $f_3 = 5a/4L$)

Example: Length: 5 m Speed of sound: 900 m/s

First Eigenfrequency: 45 Hz





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Compressible Fluids









For oscillations and resonance phenomena compressibility can be very significant

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Compressible Navier-Stokes equations

Mass conservation:

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i) = 0$$

Momentum conservation:

$$\rho \left(\frac{\partial u_{i}}{\partial t} + u_{j} \frac{\partial u_{i}}{\partial x_{j}} \right) = -\frac{\partial p}{\partial x_{i}} - \rho \frac{\partial \Psi}{\partial x_{i}} + \frac{\partial}{\partial x_{j}} \left[\mu \left(\frac{\partial u_{i}}{\partial x_{j}} + \frac{\partial u_{j}}{\partial x_{i}} \right) - \frac{2}{3} \mu \frac{\partial u_{k}}{\partial x_{k}} \delta_{ij} \right]$$

Equation of state (e. g. ideal gas law):
$$p = \rho R T$$

Energy conservation:
$$\frac{\partial T}{\partial t} + u_{j} \frac{\partial T}{\partial x_{j}} - \alpha \left(\frac{\partial}{\partial x_{j}} \frac{\partial T}{\partial x_{j}} \right) = \Phi$$

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Incompressible flow

Incompressible flow:

Compressible mass conservation:

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i) = 0$$

 $\rho \neq f(p), \rho \neq f(t)$

Mostly:



This results in

Continuity equation:
$$\frac{\partial u_i}{\partial x_i} = 0$$

Momentum equations: $\rho \left(\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} \right) = -\frac{\partial p}{\partial x_i} - \rho \frac{\partial \Psi}{\partial x_i} + \frac{\partial}{\partial x_j} \left[\mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \right]$





Dimensionless equations

The equations were made dimensionless by

- a characteristic length L and
- a characteristic velocity Û

$$u_{i}^{*} = \frac{u_{i}}{\hat{U}} \qquad t^{*} = \frac{t}{(L/\hat{U})} x_{i}^{*} = \frac{x_{i}}{L} \qquad p^{*} = \frac{p}{(\rho\hat{U}^{2})}$$





Dimensionless equations

Introduced into the Navier-Stokes equations results in

$$\frac{\partial u_i^*}{\partial t^*} + u_j^* \frac{\partial u_i^*}{\partial x_j^*} = \frac{\partial p^*}{\partial x_i^*} + \frac{\partial}{\partial x_j^*} \left[\frac{1}{Re} \left(\frac{\partial u_i^*}{\partial x_j^*} + \frac{\partial u_j^*}{\partial x_i^*} \right) \right]$$
$$\frac{\partial u_i^*}{\partial x_i^*} = 0$$
$$\hat{U}L$$

With the Reynolds number

 $Re = \frac{OL}{V}$



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The only relevant characteristic number for incompressible flows is the Reynolds number

Problem: No conditional equation for the pressure





Methods for calculation the pressure

• Artificial compressibility

Explicit, Implicit

- Poisson equation for the pressure
- Pressure correction methods

Usawa

SIMPLE, SIMPLEC, SIMPLEST, PISO

• others

Fractional Step Method

etc

Based on

Physical approximation

Physical modelling

Numerical approximation





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"Physical" approximation

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Artificial compressibility

Continuity equation (Compressible)

Artificial compressibility

Modified continuity equation

Momentum equation

Correct steady state solution:

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i) = 0$$

$$\frac{\partial \mathbf{p}}{\partial \rho} = \mathbf{a}_{k}^{2}$$

a_k ... Artificial compressibility Numerical coefficient

$$\frac{1}{a_{k}^{2}}\frac{\partial p}{\partial t} + \frac{\partial u_{i}}{\partial x_{i}} = 0$$

$$\rho\left(\frac{\partial u_{i}}{\partial t} + u_{j}\frac{\partial u_{i}}{\partial x_{j}}\right) = -\frac{\partial p}{\partial x_{i}} + \frac{\partial}{\partial x_{j}}\left[\mu\left(\frac{\partial u_{i}}{\partial x_{j}} + \frac{\partial u_{j}}{\partial x_{i}}\right)\right]$$
solution:
$$\frac{1}{a_{k}^{2}}\frac{\partial p}{\partial t} \rightarrow 0 \quad \Rightarrow \text{ exact Solution}$$

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Artificial compressibility

For unsteady problems

Introduction of a Pseudo time $\boldsymbol{\tau}$

Modified continuity equation

$$\frac{1}{a_{k}^{2}}\frac{\partial p}{\partial \tau} + \frac{\partial u_{i}}{\partial x_{i}} = 0$$

Momentum equations

$$\rho \left(\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} \right) = -\frac{\partial p}{\partial x_i} + \frac{\partial}{\partial x_j} \left[\mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \right]$$
$$\frac{1}{a_k^2} \frac{\partial p}{\partial \tau} \to 0 \qquad => \text{Exact Solution}$$

Integration in each time step

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Artificial compressibility Time step **Pseudo time step** $\frac{1}{a_k^2}\frac{\partial p}{\partial \tau} \! + \! \frac{\partial u_i}{\partial x_i} = 0$ $\frac{\partial \mathbf{u}_{i}}{\partial t} + \mathbf{u}_{j} \frac{\partial \mathbf{u}_{i}}{\partial \mathbf{x}_{i}} = -\frac{\partial \mathbf{p}}{\partial \mathbf{x}_{i}} + \frac{\partial}{\partial \mathbf{x}_{i}} \left| \mu \left(\frac{\partial \mathbf{u}_{i}}{\partial \mathbf{x}_{i}} + \frac{\partial \mathbf{u}_{j}}{\partial \mathbf{x}_{i}} \right) \right|$ explicit or implicit Time discretization is possible





Methods for calculation the pressure

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Poisson equation for the pressure

Taking the momentum equation and derive it

$$\rho \left(\frac{\partial u_{i}}{\partial t} + u_{j} \frac{\partial u_{i}}{\partial x_{j}} \right) = -\frac{\partial p}{\partial x_{i}} + \frac{\partial}{\partial x_{j}} \left[\mu \left(\frac{\partial u_{i}}{\partial x_{j}} + \frac{\partial u_{j}}{\partial x_{i}} \right) \right]$$

Differentiate the x – equation with respect to x, Differentiate the y – equation with respect to yDifferentiate the z – equation with respect to z

Sum up the resulting equations leads to

$$\frac{1}{\rho} \frac{\partial^2 p}{\partial x_i \partial x_i} = -\frac{\partial}{\partial x_i} \left(u_j \frac{\partial u_i}{\partial x_j} \right) + \frac{\partial}{\partial x_i} \left(\frac{\partial}{\partial x_j} \left[\nu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \right] \right) \qquad \stackrel{\text{Exall equation of the set of$$

Exact equation for the pressure





Poisson equation for the pressure

$$\frac{1}{\rho} \frac{\partial^2 p}{\partial x_i \partial x_i} = -\frac{\partial}{\partial x_i} \left(u_j \frac{\partial u_i}{\partial x_j} \right) + \frac{\partial}{\partial x_i} \left(\frac{\partial}{\partial x_j} \left[v \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \right] \right)$$

With the continuity equation

$$\frac{\partial u_i}{\partial x_i} = 0$$

One obtains the conditional equation for the pressure

$$\frac{1}{\rho} \frac{\partial^2 p}{\partial x_i \partial x_i} = -\frac{\partial}{\partial x_i} \left(u_j \frac{\partial u_i}{\partial x_j} \right)$$

Needed: 2nd order derivatives of velocity

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Poisson equation for the pressure

Coupled system, solved iteratively

Velocity is a function of pressure

Pressure is a function of velocity

$$U_i = f(P)$$
$$P = f(U_i)$$



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Poisson equation for the pressure







Poisson equation for the pressure



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Pressure correction methods

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Physical approximation

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Pressure correction methods



Conditional equation for the velocities

Pressure represents a parameter to fulfill the continuity equation

Mathematical: Pressure is a Lagrange Multiplier





Pressure correction methods



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Uzawa algorithm

Discretized equations

$$\begin{bmatrix} \underline{A} & \underline{H} \\ \underline{Q} & 0 \end{bmatrix} \begin{bmatrix} \underline{U} \\ \underline{P} \end{bmatrix} = \begin{bmatrix} \underline{b} \\ \underline{0} \end{bmatrix}$$

Momentum equations

Continuity equation

Calculation of the velocities from the momentum equation (1. row)

$$\underline{U} = \underline{A}^{-1}\underline{b} - \underline{A}^{-1}\underline{H}\underline{P}$$

Introduced into the continuity equation (2. row) results in an equation for the pressure

$$\left(\underline{Q}\underline{A}^{-1}\underline{H}\right)\underline{P} = \underline{Q}\underline{A}^{-1}\underline{b}$$

This equation is very complex and must be solved iteratively.





Uzawa Algorithmus

Pre-conditioned Richardson iteration:

Assumption: P^0

Calculation: $\underline{P}^{n+1} = \underline{P}^n - \underline{\rho}\underline{r}^n$ with $\underline{r}^n = \underline{Q}\underline{U}^n$ Conditioning matrix Local continuity error

Acceleration of the convergence by penalization





Uzawa algorithm



Suitable choice of conditioning matrix:

$$\underline{\rho} = \lambda \underline{\underline{E}}$$

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Pressure correction

Two – stage correction methods

Discretized equations



Momentum equation

LU – Decomposition (lower and upper triangle matrices)

$$\begin{bmatrix} \underline{A} & 0 \\ \underline{Q} & -\underline{Q}\underline{A}^{-1}\underline{H} \end{bmatrix} \begin{bmatrix} \underline{E} & \underline{A}^{-1}\underline{H} \\ 0 & \underline{E} \end{bmatrix} \begin{bmatrix} \underline{U}^{n+1} \\ \underline{P}^{n+1} \end{bmatrix} = \begin{bmatrix} \underline{b} \\ \underline{0} \end{bmatrix}$$
$$\begin{bmatrix} \underline{U}^{n+1} \\ \underline{P}^{n+1} \end{bmatrix} = \begin{bmatrix} \underline{b} \\ \underline{0} \end{bmatrix}$$





Pressure correction

Forward substitution

$$\begin{bmatrix} \underline{A} & 0 \\ \underline{Q} & -\underline{Q}\underline{A}^{-1}\underline{H} \end{bmatrix} \begin{bmatrix} \underline{U}^* \\ \underline{P}^* \end{bmatrix} = \begin{bmatrix} \underline{b} \\ \underline{0} \end{bmatrix}$$
$$\begin{bmatrix} \underline{E} & \underline{A}^{-1}\underline{H} \\ 0 & E \end{bmatrix} \begin{bmatrix} \underline{U}^{n+1} \\ \underline{P}^{n+1} \end{bmatrix} = \begin{bmatrix} \underline{U}^* \\ \underline{P}^* \end{bmatrix}$$

Backward substitution

Procedure

$$\underline{\underline{A}}\underline{\underline{U}}^{*} = \underline{\underline{b}}$$

$$\underline{\underline{Q}}\underline{\underline{A}}^{-1}\underline{\underline{H}}\underline{\underline{P}}^{*} = \underline{\underline{Q}}\underline{\underline{U}}^{*}$$

$$\underline{\underline{P}}^{n+1} = \underline{\underline{P}}^{*}$$

$$\underline{\underline{U}}^{n+1} = \underline{\underline{U}}^{*} - \underline{\underline{A}}^{-1}\underline{\underline{H}}\underline{\underline{P}}^{n+1}$$





Pressure correction

- Calculation of A⁻¹ to expensive
- => Approximation of A^{-1}



Various pressure correction methods differ by the choice of the approximation for ${\rm B_1}$ und ${\rm B_2}$





Simplest choice for unsteady flow (projection method)

$$\underline{\underline{B}}_1 = \underline{\underline{B}}_2 \approx \Delta t \underline{\underline{E}}$$







Implicit pressure-based scheme for NS equations (SIMPLE)

SIMPLE: Semi-Implicit Method for Pressure-Linked Equations









Implicit pressure-based scheme for NS equations (PISO)

PISO: Pressure Implicit with Splitting Operators













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45⁴







Ruchonnet, N. et al., Simulation of phase resonance in radial hydraulic machines, Vienna Hydro 2014



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Compressible calculation



Ruchonnet, N. et al., Simulation of phase resonance in radial hydraulic machines, Vienna Hydro 2014



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Coupled compressible – incompressible calculation













Ellbow draft tube

- Unstable flow can result in a vortex rope
- Vortex rope leads to a rotating pressure field
- Dynamic loading on the draft tube structure
- Synchronous pressure pulsation

at the draft tube inlet



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If the excitation is in resonance with the penstock, it can result in extreme pressure amplitudes













Incompressible Flows

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<u>Summary</u>

• Relevant physical effects determine if a flow shall be treated incompressible or compressible

Applying compressible calculation for low Ma leads to stiff problems, immense computational effort

- Gas flows can be treated incompressible up to a Ma = 0.3
- Liquid flows must be treated compressible when pressure waves plays an important role (resonance phenomena)
- Physical relevance For incompressible flows there exists no direct equation to determine the pressure. Therefore, a special treatment is required:
 - Artificial compressibility
 - Pressure correction
 - Poisson equation
 - Others
- Coupled simulations (partly compressible, partly incompressible) can be a good compromise